TECHNOLOGY CAPABILITY NEEDS OF FUTURE EARTH SCIENCE MISSIONS

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Abstract

Technology capability needs for future earth science space missions have been collected as an input to NASA's New Millennium Program. Candidate technologies to meet these capability needs have been identified and a set of candidate mission architectures developed. This paper describes the process that was used to develop the capability needs and lists the needs that resulted from that process. These capability needs are presented and discussed to encourage the development of new technologies to meet tbc needs.

New Millennium Program

NASA's New Millennium Program has the goal of revolutionizing spare and earth science programs to achieve exciting and frequent missions in the 21st century. The approach taken involves demonstrating and validating revolutionary technologies in order to reduce development time. s and life cycle mission costs. The program aims to demonstrate high value technologies through a series of near term validation flights where technology demonstration is the overriding mission goal. The technology validation projects are carried out with the support of Integrated Product Development Teams (IPDTs) which are responsible, for identifying and supplying high value technologies to the flight system development teams.

Capability Needs Development Process

The New Millennium program began with a deep space emphasis but it has recently begun to focus on the needs of NASA's Mission 10 Planet Barth (MTPE) Enterprise. Because of future budgetary constraints, the MTPE program has established the goals of ensuring continuity of existing critical Barth observing System (EOS) measurements at reduced cost as well as performing additional important measurements enabled by new technology.

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The response of New Millennium to meet the MTPE goals is to demonstrate technologies of specific value. to future earth science missions in a series of low cost, rapidturnaround earth orbiting missions.

The first step in **focusing** on earth science **needs** was to collect the. views of the major constituencies, One of these was represented by a group of earth scientists who metat a workshop in Landover Maryland in March 1995 at tile invitation of the New Millennium program. This group identified the technology capability needs of fourteen future earth science mission or measurement themes. A matrix showing the mission science themes vs. capability needs is given in 'l'able 1. The assembled group and a subsequent Science Working Group meeting in Pasadena in April, 1995, identified seven of these missions as most likely to be a candidate for a near term New Millennium demonstration mission. These seven arc identified on the right hand part of Table i. The subsequent work with this constituency to quantify capability needs and identify appropriate technologies concentrated on this shorter list of seven mission science themes,

The other major constituency was the Mission to Planet Earth program office. The centerpiece of the MTPE is the Earth Observing System, whose prime goal for technology development is to continue the highly calibrated EOS measurements indefinitely at greatly reduced cost. Another initiative, the Earth System Science Pathfinder (IASP), will utilize advanced technology to enable totalty new measurements. The process of identifying needs and technologies followed by the MTPE program office is described below.

The Mission to Planet Earth Program - A Technology Needs Assessment

The MTPE program seeks to further understanding of our planet as an integrated system consisting of

Table 1. Eart	h Se	ciei	ice	Mi	SSIC	m (ec i	Cap viss	abi lon	у	Re ss	qui	rements	1	ľ	y
REQUIRED CAPABILITIE S	Α	1110	i	ĺ	(CIT		16	RE	16	AI M		HERIC SCIENCES1
	۱.1	2	İ	1	2	3	M	G1	1	2	3	4	ΑI		Atmospheric Sounder
'ACECEME I CAPAHI111 IE'S									1				A?		TroposphericPollutants
rligh efficiency powersystem											•		А3		1 ropospheric Winds LIDAR
Mass data storage	₽										•		11		
GPS (on a-chip)	•	1						•		1	•		OCE	. :	SCIENCE S
GPS AttitudeDetermination	D	(•		F	•	1	01		Surface Wind
Precision Spacecraft pointing								•					0?		Sea Ice t lazard Mapping
Low cost 3-axis stabilization													03		Ocean Color
TightFornationFitightSubsystems			ļ					•		1		F.	04	ļ	In-SituData Relay
EfficientMicro-propulsion								•					11	[
Drag-free Compensation								•		1			GRM	. '	MAPPING
Extremely High Bandwidth Communications								l		•			G1		Ocean and LandSurface
III SituSensorInterrogation/Uplink															Gravity Mapping
lether													1		DIAL COLLABOR
Inflatable Structures											•		TER	5	TRIAL SCIENCES
AtomicOxygen flesistant Materials								•		•	•		11		Soil Moisture
ENSOR CAPABILITIES													12		SAR Topographic Mapping
Reliable long-lived solid-state lasers								ļ					L3		SAR Biomass
Light 1 hermally Stable Optical Materials	•	•)						•	L4		Landsat Pathfinder
Cryocoolers - miniature, long-lived, vib -isolated	•	•				•						•	15		Geomagnetism
UV, VIS, IR, FIR Detectors & Focal Plane Arrays	•	•											9.1		Laser Altimetry 1 opoMappi
Compact hi-resolution spectrometer	•	•										•			1
liber based wide angle optics												•			1 14 feed on the control of the control
High performance narrow band optical filters	•	•								_					Workshop candidates for early New Millennium
Antennas, Lightweight & Deployable		•								•	_				
Active Microwave				•					l _	•	•				flightdemonstrations
Large Passive Microwave	•			•					•						
Miniaturized SAR					'					•	•				
Lowiniass, athermal, telescopes Superconducting gravity gradiometer	•	•													Į. Į. Į.
. Terahertz oscitlators	١.							•							
Teranertz oscillators ± ligh-efficiericy diode and optical m⊧xers															
MiniaturizedFields and ParticlesInstruments	•	-													
Accelerameter															
PRECEIPTOMETER PERMAN IONS CAFAFIII111 S									-						
On-board processing		•		•						•		•			
Autonomous Spacecraft/Mission operations		•		•				•				•			
Spacecraft Constellation Operations		1													
Efficient End-to-end Data Management	•	•		•	•			•	•	•	•	•			
Distributed Real-time Downlink					•	•			•	•		•			

land, oceans, and atmosphere and to monitor global change. Recently, a comprehensive reshaping effort was completed that aligned program requirements with projected budgetary constraints. This activity identified new technology development as a key ingredient to offset anticipated financial limitations. Internal and external review teams postulated that, if nurtur ed, new and innovative subsystem and system architectures would merge.ml allow many of the stated program objectives to be achieved with Iess complex flight segments requiring shorter development time. Concurrent reductions in system size, mass, power, and consumables would also enable the use of smaller spacecraft and launch vehicles. More autonomous ground operations were also envisioned to reduce traditional staffing levels. In response to this vision of the future, a systematic, toplevel, prc~grwn-wide Technology Infusion Plan was pr~'paled to initiate the process of identifying key technology advancements for Earth science missions. A hierarchical approach, shown pictorially in Figure 1, was taken where mission objectives guide the selection of instrument technology needs which, in turn, influence

complementary advancements in spacecraft and ground system capabilities. A focused, requirements driven approach with direct project or user connectivity was sought to effectively harness supplier capabilities and to leverage available funds so that useful end products would result. The process started with a technology needs survey performed by the Goddard Space Flight Center (G SFC) MTPE program office. Contributions were actively solicited from the Earth science community and other user groups, flight projects, and the ground operations team so that all elements received proper representation.

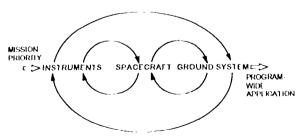


Figure 1. Technology Development Dynamics

After a series of meetings and workshops, some candidate mission sets were proposed that assisted in the prioritization process. Advancements in instrument and sensor technologies were judged to have the highest potential payback to the MTPE program because, historically, state-of-the-art scientific instruments have long development times and drive the requirements for supporting spacecraft and ground systems. In order to further define specific technology needs, a survey form was prepared and distributed widely. The collected results of that survey showed trhat the desired technologies fell mainly into the four general categories listed below:

(a) microelectronic devices and innovative packaging that provide significant reductions in overall volume, mass, and power for the whole spectrum of Parth observing instruments

 (b) detector systems that cover the wavelength bands of interest to Farth science that require minimal or no active cooling,

(c) detector arrays that eliminate the need for scanning mechanisms, and

(d) higher image resolution devices.

Associated spacecraft and ground system technologies that would complement advanced instrument and sensor development and, at the same time, enhance the scientific mission were also identified. Priority items included improvements in orbit determination, attitude knowledge, data handling and storage, and level of on-board autonomy.

To illustrate how this hierarchical technology assessment process works, application to a recently approved New Millennium advanced land imaging flight validation mission (Farth Orbiter-1) is described below.

hyperspectral detectors arranged on a partially populated employs a pushbroom combination of multispectral and Fahanced Thematic Mapper (FTM+) for future land instrument that could be flown in place of the Landsat advanced technology could be employed to develop an It was determined, via a peer review process, that uncooled focal plane and covering the wavelength range imaging missions. The proposed baseline instrument space as well as ground viewing. When compared to the Radiometric calibration of 5% or better is achieved by optical system of hot pressed silicon carbide provides a ground system technologies under consideration that about a factor of 8. Complementary spacecraft and and reduces volume, mass, and power requirements by climinates the need for a scan mirror and radiative cooler present generation ETM+, the new instrument concept incorporation of devices that allow sun, moon, and deep from 0.4 to 2.5 micrometers. A three mirror anastigmatic support this instrument include an advanced fiber optic rigid, and thermally stable configuration.

data bus to handle the high data rates generated by the land imager, data compression, an X-band phased array, cloud editing, auto navigation and control, and increased levels of on-board spacecraft autonomy to name a few. Validation of these technologies will have a synergistic effect on future MTPE programs.

The process outlined above is being applied to other high priority Farth science missions and will spawn additional advancements in instrument, spacecraft, and ground system capabilities that can then be infused into the missions of the future.

Capability Needs vs. Technology Needs

The stated needs of the future missions are a combination of capability needs and technology needs. The difference between these two is both real and artificial. Capability needs, such as "downlink with a data rate of 600 Mb/s" are theoretically independent of technology. That is, the capability could be provided by more than one distinct technology, e.g. optical or RF. If RF, then different frequencies could be used. Technology needs are more near term and assume a particular technology, e.g. "a Ka-band phased array antenna." On the other hand, the statement of the quantitative capability need, i.e. "600 Mb/s," is generally made by someone who knows the capabilities and limitations of particular technologies.

The two approaches are obviously intertwined. In the collection of needs the capabilities were stressed, so that revolutionary new technologies to meet the need could be identified. One of the purposes of this paper is to expose the needs to a broader audience so that exciting new technologies can be proposed for future demonstration missions.

Integrated Capability Needs

The next step in the process was to integrate and quantify the two sets of capability needs, one from the science working group and one from the MTPE program office, so that specific technology validation experiments could be identified.

The information for this step was obtained by further, detailed discussions with scientists and instrument developers involved with the science measurement themes listed above. The results of this effort are shown in Tables 2, 3 and 4.

The capability needs are grouped into sensor capabilities, spacecraft capabilities and operations capabilities. There is clearly some overlap between all of these, especially as higher degrees of flight system integration are desired. The grouping should be seen as one of convenience only without any implication as to the best location for capabilities.

The middle column contains the level of capability that would satisfy most of the future missions that were studied. The last column shows a capability that is desired by only one or two future missions. In other words, a technology demonstration that provided the capability shown in the middle column would provide a valuable step forward while one that met the capability shown in the right band column would satisfy even the most demanding of the future science missions that were surveyed. In the following sections the furthe discussion and rationale for the capability needs is given.

Sensor Capability Needs

The integrated needs of science instruments arc. presented in '1'able. 2. The.sc. capabilities and technologies were identified as those that would result in smaller, lighter, simpler, less costly, more reliable future science instruments. It will be clear in the table that most of the needs arc strongly attached to a particular technique, for example lightweight, the.rlnally stable optical materials are needed for

optical sensors whereas techniques such as inflatable antennas arc needed for microwave sensors. Thus some selection between measurement techniques is inherent in prioritizing the technologies.

Rationale for Sensor Capability Need s

Materials

Materials with light weight and low thermal expansion at c dc.sired fot optical instrument structures, optics and integrated optical structural assemblies. Silicon Carbide is seen as a major candidate to meet these needs.

Optics

optical designs withwide fields of view can be used to eliminate scanning minor assemblies, thus greatly reducing complexity, mass and cost.

Optical Elements

Wedge fillers are desired 10 provide spectrometer functionality in a greatly reduced size. High performance, narrow hand optical filters are desired for future instruments that rely on detecting either I a s e r backscatter or thermal emission from the atmosphere.

'1'able '2	2, Integrated Sensor Capabilit y Needs	
Capability	General Need	Limited Need
Large Area PushbroomImaging Spectrometers	Multispectral Arrays	Hyperspectral A trays Wedge Filters
Wide Angle optics	151040 dc.glees	
Stable, Light Weight Optics and Support Structures	Silicon Carbide or Composite Elements	
Improved UV, Visible, IR, and Microwave Detectors	Uncooled	QWIP (3 to 16 microns) MMIC (54 to 183 Gbz)
Superconducting Bolometers	Low Power Local Oscillators	
13nhauced Cryocoolers	5s to 80 K 5 Year Lifetime Low Vibratory Disturbance	30 1045 K
Solid State 1 .asers	(). Sto 2 microns 10日 1() pulses 3 to 5% Efficiency	2.5 Thz 1 meal oscillators
Optical Mixers and Multipliers		2.5 Thz
Narrow Band Optical Filters	().?.9 m 0.32 microns 0.82 to 0.94 microns	
Improved, Less Costly Calibration Techniques	0.4 to 10 microns	5% Radiometric Accuracy 1% Radiometric Stability
High Speed Analog to Digital Converters	>1? bits	>14 bits (>1 Mhz) 20 bits (0.? Mhz)
Data Compression ASICS	1 ossless	Lossy

Detectors

Improved low cost, detectors are required especially for certain parts of the frequency spectrum, namely Quantum Well Infrared Photodetectors (QWIP) for long wavelength infrared and Monolithic Microwave Integrated Circuits (MMIC) for millimeter wavelength.

Coolers

Long lived, lightweight, low cost vibrationless eryocoolers are desired mostly for cooling infrared detectors.

Antennas

Lightweight, low cost, deployable microwave antennas are required for future SAR, radar and passive microwave instruments. Stable phase center antennas are required for missions requiring very precise distance measurements using RP links.

RF Components

More efficient, low cost RF components are needed for future SAR, radar and passive microwave instruments.

Lascis

Reliable, power efficient, lighter weight lasers are the key components in lidars for wind, acrosol and precise topography measurement.

Controls

Autonomous optical alignment is required to maintain alignment for laser backscatter collectors.

Mechanisms

Miniaturized mechanical devices, such as piczoelectrics are desired for a number of applications, including compact Fourier Transform Spectrometers for atmospheric temperature and chemistry studies.

Accelerometers

Sensitive lightweight accelerometers are required for missions requiring detection and perhaps compensation of very small forces acting on the satellite.

Electronics

High speed, low cost, reliable highly integrated electronics are required for the signal chains and command and data sections of all sensors.

Spacecraft Capability Needs

Table 3 contains what were considered the major areas where advances in spacecraft capability would enable either new missions now considered unaffordable or the continuation of present

measurements at greatly reduced cost. In some cases the improvements are called out in traditional subsystems, such as power sources, while in others a new cross subsystem architecture is implied, such as multi-functional structures or very small spacecraft. Rationale for Spacecraft Capability Needs

Power

More efficient power systems are needed for all missions but are seen as enabling for those missions that use large amounts of power. These are represented by active sensors such as synthetic aperture radars (SAR) and lidars. The missions that would use them are of the long term monitoring variety, thus the need for batteries with high cycle life.

Attitude and Orbit Determination

The future missions desire on-board attitude and orbit determination approaches that are low cost and easily adaptable to new missions. Combination of functions, such as can be done with GPS receivers that can provide both position and attitude, is seen as a promising approach to that objective. The need for very precise attitude knowledge stems from the desire to co-register pixels from different instruments on different platforms flying in formation.

Propulsion

Two needs were identified for propulsion capabilities, one for very low thrust, lightweight propulsion components and the other for drag compensation methods. The former is required for low cost microspacecraft. The latter is required for lower cost orbit maintenance and also to enable missions such as gravity measurement which operate at low altitude, around 300 km, in a high drag environment. Drag needs to be compensated both to provide reasonable mission lifetimes and also to remove a major source of experimental error.

Command and Data Handling

The need for high capacity, high rate data storage devices and high rate data busses comes primarily from SARs and hyperspectral imagers. Both of these have the potential for collecting data over large swaths, from 50 to 200 km with resolution as low as 10 to 30m. Instrument concepts have been developed with data rates up to hundreds of Mbits per second. Efficient mission architectures, with downlinks only about once a day, require lightweight reliable low cost on-board memories of hundreds of Gbits capacity.

Capability '1	able 3. Spacecraft Capability Needs General Need	Limited Need
Resource Efficient Power Generation	4010 50 W/kg	60 to 80 W/kg >1 kw payload power
Improved Energy Storage Capacity	40 m 60 Whr/kg up to 30, 000 cycles	701090 Whr/kg
Precise Orbit 1 Determination	3 to 5 m	1to 0.1 m
Miniaturized Attitude Control	GPS on a chip or equivalent 0.1 degree	0.01 to 0.003 degree for pixel coregistration
Advanced Propulsion Systems	High Specific Impulse (500" to 1000 s) 1 to 22 N Thrust Levels	0.1 N
Increased Mass Data Storage	Up to 200 GB	Up to 2 TB
1 inhanced On-Board Flight Computer	32 bit	
HighBandwidthData Systems	50 Mb/s MIL-STD-1773 with Backward Compatibility Interface Simplification ATM Protocol	300 10600" M h/S
High Bandwidth Communications	50 to 150 Mb/s X-Band Phased Array Ka-Band Phased Amy (25.5 to 27 Ghz) Associated Ka-Band Flight Components	300 to 600 M b/s
Atomic Oxygen Resistant Materials and Stable Coatings	400 to 1000 km Altitude (Polar orbits)	2S() to 350 km Altitude
Integrated Multi-Functional Structures	Mechanical, Electrical, Thermal	
Formation Flying Separation Maintenance	2500 km	500 m
Very Small, 1 low Cost Spacecraft		Less than 10 kg; ~\$100K each

Telecommunications

The future investigations desire fixed nml-deployable high gain antennas that can be steered electronically to reduce the mass, power, cost, risk and complexity of present high gain and low gain antennas. Applications include both TDRSS and direct to the ground. Most moderate data rate missions are well served by rates in the range of 50 to 150 Mb/s while

the aforementioned SAR and hyperspectral imagers need rates as high as 600 Mb/s.

Materials

The need for materials also stems from the desire to operate at low altitudes. Some of these missions require large deployable antennas and structures made of plastic materials, such as inflatables. Present

materials are susceptible 10 degradation by atomic ox ygen.

Multifunctional Structures

Present spacecraft arc designed, built and testedalong lines that stress functional and subsystem separation. As spacecraft become smaller tbc structures and the teams that build tbcm must become more highly integrated.

Formation Flying

Formation flying covers a spectrum of mission architectures, all using more than one spacecraft that together form a larger measurement system. This capability is desired for several reasons. The first is to enable the potential to replace individual EOS instruments without having to replace entire multi-instrument platforms. The second reason is (o allow the eventual replacement of the large multi-instrument platforms with a number of much smaller cooperating single instrument platforms. The third reason is to enable science measurements that by their nature rely on multiple. spacecraft, such as interferometric SAR and gravity measurement.

Very Small Spacecraft

Some future mission architectures require the dispersion of many small satellites so that simultaneous, geographically separated measurements can be take.n. In order to build, launch and operate such satellite constellations, each one must a) cost hundreds of thousands, not millions; b) weigh kilograms, nothundreds of kilograms and c) operate autonomously.

Operations Capability Needs

Table 4 contains operations capability needs that are expected to result in more autonomous, Self maintaining flight systems, easier, lower cost access to ground antennas and more efficient ground transport of data.

On-Board Processing

Several of the missions can make use of very powerful cm-board processors, either general purpose or dedicated designs. Processors with "GigaFLOPS" equivalent" processing speed can be used to perform the type of processing that is now done (m the ground before, any scientific or operational usc of the data is made. 1 Examples are processing of SAR data to the image stage or operations cm specially weighted combinations of spectral data from hyperspectral imagers. It is difficult to quantify the processing speed needed for these types of processors because two different technology paths might be used to provide the capability, eitherver y powerful general purpose, computers or specially designed digital signal processors. The choice between these should **consider** technology development or non recurring cost,

recurring cost of eachnew device as well as the mass and power of the flight devices.

Autonomy

Each of the future missions desires to operate with a high degree of autonomy so that routine operations, maintenance and health monitoring can be done efficiently. ~'here is also the desire to command the spacecraft at a high level, so that operations team sizes are reduced and the scientists can be in more direct control of their experiments.

Ground Stations

1 lower cost, autonomous ground stations will reduce cost by allowing more ground stations to be widely dispersed at tbc most efficient locations and operated by smaller staff. Higher downlink rates allow tbc data to be transferred with fewer passes and less usc of ground station time.

Ground Data Handling

Improvements in ground data handling, including both storage and distribution are needed to efficiently handle large data volumes and to distribute data quickly to dispersed data users.

Interactive Access

The users of data from space borne instruments desire. to command the investigations at a high level and have widely dispersed access to data over global networks.

Strawman Mission Architecture Development
Once the capability needs were identified, they were
transmitted to the IPDTs so that they could identify
technologies to supply the appropriate functionality
and performance. Concurrent with the 11'1)1' activity a
series of technology validation mission architectures
was define.d (o help focus the discussion. These
mission architectures provided tbc IPDT technology
developers with enough of a mission context to
develop concepts and costs for actual technology
demonstrations.

The validation mission architectures—are briefly described in '1'able 5. Each one is built around a science measurement theme, including as its centerpiece an advanced instrument and then key supporting technologies. Some of the important features of these mission architectures are the following: a) short mission development cycles with a goal for the first launch date in late 1998; b) small, low cost launch vehicles, the biggest being of the LMLV/Taurus class, the smallest of the half-l>c~asus class; c) short mission lifetimes determined by the time required to validate the technology and d) each mission demonstrating a n advanced end-to-end science measurement with no science

requirements as such, only those necessary to demonstrate an approach relative to a known standard.

'1'able 4. operations Capability Needs

General Need Limited Need Capability

3 to 10 GIIJOPS-equivalent Enhanced On-Board Processing 1 GFLOPS-equivalent

Efficient Load Processing **Fusion of Multiple Data Streams**

Progressive Flight Segment Scheduling and Sequencing Cloud and Feature Editing Station Keeping and Formation Flying

}'light Segment Health Autonom y

Summarization

FaultDetection, isolation, and

Recovery

Auto Navigation and Control

300 to 600 Mbps Downlink Low Cost Ground Stations Global Coverage

50-150 Mbps Downlink

0.5 TB/day 2 TB/day Advancements in Storage

Management and Technology Interoperability of Commercial

Media and Software

Improvements in interactive Access Standardized Interfaces

Networking

Table 5. Summary of trawman Mission Architectures

	rabic 3. Sullilliary of	trawman wission Architectures	
MISSION TITLE	KEY SCIENCE VISION AD DRESSED	KEY TECHNOLOGY VALIDATION	COMMENTS
LAND IMAGING	LAND SURFACE CHARACTER IZATION AND USE; BIO PRODUCTIVITY	ADVANCED IMAGER FORMATION FLYING	POTENTIAL REPLACEMENT FOR LAN DSAT 8
ATMOSPHERIC NADIR SOUNDING	TEMPERATURE AND MOISTURE PROFILING	LIGHTWEIGHT COMPACT SPECTROMETER LONG WA VELENGTHOETECTORS FORMATTON FLYING	POTENTIAL INFUSION INTO NPOESS MONITORING SATELLITES
TROPOSPHERIC CHEMISTRY	TROPOSPHERIC OZONE AND POLLUTANT MAPPING	LIGHTWEIGHT COMPACT SPECTROMETER LONG WAVELENGTH DETECTORS	
TROPOSPHERIC WINDS	TROPICAL TROPOSPHERIC WINDS	LIGHTWEIGHT SOLID STATE LASER AND TELESCOPE	TECH DEMONSTRATION FOR MISSING EOS MEASUREMENT GOAL
GPS CO nstellation/atmos Sounding	HIGH SPATIAL AND TEMPORAL RESOLUTION TEMPERATURE PROFILING	VERY SMALL S/C S/C CO NSTELLATION GPS ON A CHIP	POTENTIAL TO INCREASE RESOLUTION AND DECREASE COST OF ATM OS. SOUNDING MEASUREMENTS
LIGHT SAR	G10BAL TOPOGRAPHY AND TOPOGRAPHIC CHANGE	LIGHTWEIGHT SAR COMPONENTS	GREATLY REDUCE COST OF FUTURE TOPOGRAPHIC CHANGE MONITORING
LARGE APERTURE/SOIL MOISTURE	G10BAL SOIL MOISTURE	VERY LARGE DE PLOYABLEANIENNA SPA RSE ARRAY AN TEN NA TECHNIQUE	TECH OEMO FOR MISSING MEASUREMENT OF HYDROLOGICAL CYCLE
FLIGHT OF OPPORTUNITY	OCEAN WIND	ADVANCED SMALL, LOW POWER INSTRUMENT/COMPONENTS ADVANCED SMALL, LOW POWER S/C COMPONENTS	OCEAN WIND AN EXAMPLE OF SMALL INSTRUMENT DEMO
FORMATION FLYING 'G RA VITY	GLOBAL GRAVITY MAPPING	CLOSE FORMATION FLYING S/C TO S/C RANGE AND RANGE RATE MEASUREMENT ACCELEROMETER	OCEAN CIRCULATION STUDIES
RADAR	WIND CLOUDS OCEAN TOPOGRAPHY	LIGHTWEIGHT RADAR COMPONENTS	

Conclusions

Capability and technology needs have been collected from the major constituencies of the Mission to Planet Barth Program to provide guidance from the future user point of view to technology developers and mission developers of the New Millennium program, Because of the reality of limited budgets, it is anticipated that some prioritization will be required and that the New Millennium missions can demonstrate only a subset of the desired future capabilities. I rooking outside of that program, the technology needs collected here can serve as a guide for technology developers. Addressing the needs described here with less resource intensive solutions

will enable exciting new missions as well as allow the continuation. Of the EOS measurements at greatly reduced cost.

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